Package ‘iterLap’

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Type Package
Title Approximate probability densities by iterated Laplace Approximations
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Description The iterLap (iterated Laplace approximation) algorithm approximates a general (possibly non-normalized) probability density on \( \mathbb{R}^p \), by repeated Laplace approximations to the difference between current approximation and true density (on log scale). The final approximation is a mixture of multivariate normal distributions and might be used for example as a proposal distribution for importance sampling (eg in Bayesian applications). The algorithm can be seen as a computational generalization of the Laplace approximation suitable for skew or multimodal densities.
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LazyLoad yes
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R topics documented:

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iterLap-package

Description

Implementation of iterLap

Details

Package: iterLap
Type: Package
Version: 1.1-2
Date: 2012-05-22
License: GPL
LazyLoad: yes

This package implements the multiple mode Laplace approximation by Gelman and Rubin (via function GRApprox) and the iterated Laplace approximation (via the function iterLap). Both functions return objects of class mixDist, which contain the fitted mode vectors and covariance matrices. Print and summary methods exist to display the contents of a mixDist object in human-readable form. Function IS performs importance sampling, using a mixDist object as input parameter.

Author(s)

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References


Examples

```R
## banana example
banana <- function(pars, b, sigma12){
  dim <- 10
  cc <- c(1/sqrt(sigma12), rep(1, dim-1))
  return(-0.5*sum((y*cc)^2))
}

start <- rbind(rep(0,10),rep(-1.5,10),rep(1.5,10))
## multiple mode Laplace approximation
gr <- GRApprox(banana, start, b = 0.03, sigma12 = 100)
## print mixDist object
```
GRApprox

**Gelman-Rubin mode approximation**

**Description**

Performs the multiple mode approximation of Gelman-Rubin (applies a Laplace approximation to each mode). The weights are determined corresponding to the height of each mode.

**Usage**

GRApprox(post, start, grad, method = c("nlminb", "nlm", "Nelder-Mead", "BFGS"),
control = list(), ...)

**Arguments**

- `post` log-posterior density.
- `start` vector of starting values if dimension=1 otherwise matrix of starting values with the starting values in the rows
- `grad` gradient of log-posterior
- `method` Which optimizer to use
- `control` Control list for the chosen optimizer
- `...` Additional arguments for log-posterior density specified in post
Value

Produces an object of class mixDist. That a list mit entries
weights Vector of weights for individual components
means Matrix of component medians of components
sigmas List containing scaling matrices
eigenHess List containing eigen decompositions of scaling matrices
dets Vector of determinants of scaling matrices
sigmainv List containing inverse scaling matrices

Author(s)

Bjoern Bornkamp

References


See Also

iterLap

Examples

```r
## log-density for banana example
banana <- function(pars, b, sigma1L) {
  dim <- 10
  cc <- c(1/sqrt(sigma1L), rep(1, dim-1))
  return(-0.5*sum((y*cc)^2))
}

start <- rbind(rep(0,10), rep(-1.5,10), rep(1.5,10))
## multiple mode Laplace approximation
aa <- GRApprox(banana, start, b = 0.03, sigma1L = 100)
## print mixDist object
aa
## summary method
summary(aa)
## importance sampling using the obtained mixDist object
## using a mixture of t distributions with 10 degrees of freedom
dd <- IS(aa, nSim=1000, df = 10, post=banana, b = 0.03,
         sigma1L = 100)
## effective sample size
dd$ESS
```
Importance Sampling and independence Metropolis Hastings sampling

Monte Carlo sampling using the iterated Laplace approximation.

**Description**

Use iterated Laplace approximation as a proposal for importance sampling or the independence Metropolis Hastings algorithm.

**Usage**

\[
\text{IS}(\text{obj}, \text{nSim}, \text{df} = 4, \text{post}, \text{vectorized} = \text{FALSE}, \text{cores} = 1, \ldots)
\]

\[
\text{IMH}(\text{obj}, \text{nSim}, \text{df} = 4, \text{post}, \text{vectorized} = \text{FALSE}, \text{cores} = 1, \ldots)
\]

**Arguments**

- **obj**
  - an object of class "mixDist"
- **nSim**
  - number of simulations
- **df**
  - degrees of freedom of the mixture of t distributions proposal
- **post**
  - log-posterior density
- **vectorized**
  - Logical determining, whether post is vectorized
- **cores**
  - number of cores you want to use to evaluate the target density (uses the mclapply function from the parallel package). For Windows machines, a value > 1 will have no effect, see mclapply help for details.
- **...**
  - additional arguments passed to post.

**Value**

A list with entries:

- **samp**: Matrix containing sampled values
- **w**: Vector of weights for values in samp
- **normconst**: normalization constant estimated based on importance sampling
- **ESS**: Effective sample size (for IS)
- **accept**: Acceptance rate (for IMH)

**Author(s)**

Bjoern Bornkamp

**Examples**

```r
## see function iterLap for an example on how to use IS and IMH
```
iterLap  

Iterated Laplace Approximation

Description

Iterated Laplace Approximation

Usage

iterLap(post, ..., GRobj = NULL, vectorized = FALSE, startVals = NULL,  
method = c("nlminb", "nlm", "Nelder-Mead", "BFGS"), control = NULL,  
nlcontrol = list())

Arguments

post  log-posterior density

...  additional arguments to log-posterior density

GRobj  object of class mixDist, for example resulting from a call to GRApprox

vectorized  Logical determining, whether post is vectorized

startVals  Starting values for GRApprox, when GRobj is not specified. Vector of starting values if dimension=1 otherwise matrix of starting values with the starting values in the rows

method  Type of optimizer to be used.

cncontrol  List with entries:

gridsize  Determines the size of the grid for each component

delta  Stopping criterion based on the maximum error on the grid

maxDim  Maximum number of components allowed (default 20)

eps  Stopping criterion based on normalization constant of approximation

info  How much information should be displayed during iterations: 0 - none, 1 - minimum information, 2 - maximum information

Value

Produces an object of class mixDist: A list with entries

weights  Vector of weights for individual components

means  Matrix of component medians of components

sigmas  List containing scaling matrices

eigenHess  List containing eigen decompositions of scaling matrices

dets  Vector of determinants of scaling matrix

sigmainv  List containing inverse scaling matrices

nlcontrol  Control list for the used optimizer.
Author(s)
Bjoern Bornkamp

References

Examples

```r
### banana example
banana <- function(pars, b, sigma12)
  dim <- 10
  cc <- c(1/sqrt(sigma12), rep(1, dim-1))
  return(-0.5*sum((y*cc)^2))
}

#########################################################################
## first perform multi mode Laplace approximation
start <- rbind(rep(0, 10), rep(-1.5, 10), rep(1.5, 10))
grobj <- GRApprox(banana, start, b = 0.03, sigma12 = 100)
## print mixDist object
grobj
## summary method
summary(grobj)
## importance sampling using the obtained mixDist object
## using a mixture of t distributions with 10 degrees of freedom
isObj <- IS(grobj, nSim=1000, df = 10, post=banana, b = 0.03, sigma12 = 100)
## effective sample size
isObj$ESS
## independence Metropolis Hastings algorithm
imObj <- IMH(isObj, nSim=1000, df = 10, post=banana, b = 0.03, sigma12 = 100)
## acceptance rate
imObj$accept

#########################################################################
## now use iterated Laplace approximation
## and use Laplace approximation above as starting point
il <- iterlap(banana, GRobj = grobj, b = 0.03, sigma12 = 100)
isObj2 <- IS(il, nSim=10000, df = 100, post=banana, b = 0.03, sigma12 = 100)
## residual resampling to obtain unweighted sample
samples <- resample(1000, isObj2)
## plot samples in the first two dimensions
plot(samples[,1], samples[,2], xlim=c(-40,40), ylim = c(-40,20))
## independence Metropolis algorithm
imObj2 <- IMH(il, nSim=1000, df = 10, post=banana, b = 0.03, sigma12 = 100)
imObj2$accept
```
resample

Description
Perform residual resampling to the result of importance sampling

Usage
resample(n, obj)

Arguments
n Number of resamples to draw
obj An object of class IS, as produced by the IS function

Value
Matrix with resampled values

Author(s)
Bjoern Bornkamp

Examples
## see function iterLap for an example on how to use resample
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