# Package 'elhmc'

August 25, 2024

eters using Hamiltonian Monte Carlo.

This function draws samples from a Empirical Likelihood Bayesian posterior distribution of param-

2 ELHMC

### Usage

```
ELHMC(
  initial,
  data,
  fun,
  dfun,
  prior,
  dprior,
  n.samples = 100,
  lf.steps = 10,
  epsilon = 0.05,
  p.variance = 1,
  tol = 10^{-5},
  detailed = FALSE,
  print.interval = 1000,
  plot.interval = 0,
  which.plot = NULL,
  FUN,
  DFUN
)
```

## **Arguments**

initial a vector containing the initial values of the parameters

data a matrix containing the data

fun the estimating function g. It takes in a parameter vector params as the first ar-

gument and a data point vector x as the second parameter. This function returns

a vector.

dfun a function that calculates the gradient of the estimating function g. It takes in a

parameter vector params as the first argument and a data point vector x as the

second argument. This function returns a matrix.

prior a function with one argument x that returns the prior densities of the parameters

of interest

dprior a function with one argument x that returns the gradients of the log densities of

the parameters of interest

n.samples number of samples to draw

1f. steps number of leap frog steps in each Hamiltonian Monte Carlo update

epsilon the leap frog step size(s). This has to be a single numeric value or a vector of

the same length as initial.

p.variance the covariance matrix of a multivariate normal distribution used to generate the

initial values of momentum  $\boldsymbol{p}$  in Hamiltonian Monte Carlo. This can also be a

single numeric value or a vector. See Details.

tol EL tolerance

 ELHMC 3

print.interval the frequency at which the results would be printed on the terminal. Defaults to

1000.

plot.interval the frequency at which the drawn samples would be plotted. The last half of the

samples drawn are plotted after each plot.interval steps. The acceptance rate is

also plotted. Defaults to 0, which means no plot.

which.plot the vector of parameters to be plotted after each plot.interval. Defaults to NULL,

which means no plot.

FUN the same as fun but takes in a matrix X instead of a vector x and returns a matrix

so that FUN(params, X)[i, ] is the same as fun(params, X[i, ]). Only one

of FUN and fun should be provided. If both are then fun is ignored.

DFUN the same as dfun but takes in a matrix X instead of a vector x and returns an

array so that DFUN(params, X)[, , i] is the same as dfun(params, X[i, ]). Only one of DFUN and dfun should be provided. If both are then dfun is ignored.

#### **Details**

Suppose there are data  $x=(x_1,x_2,...,x_n)$  where  $x_i$  takes values in  $R^p$  and follow probability distribution F. Also, F comes from a family of distributions that depends on a parameter  $\theta=(\theta_1,...,\theta_d)$  and there is a smooth function  $g(x_i,\theta)=(g_1(x_i,\theta),...,g_q(x_i,\theta))^T$  that satisfies  $E_F[q(x_i,\theta)]=0$  for i=1,...,n.

ELHMC draws samples from a Empirical Likelihood Bayesian posterior distribution of the parameter  $\theta$ , given the data x as data, the smoothing function g as fun, and the gradient of g as dfun or  $G(X) = (g(x_1), g(x_2), ..., g(x_n))^T$  as FUN and the gradient of G as DFUN.

#### Value

The function returns a list with the following elements:

samples A matrix containing the parameter samples

acceptance.rate

The acceptance rate

call The matched call

If detailed = TRUE, the list contains these extra elements:

proposed A matrix containing the proposed values at n. samaples - 1 Hamiltonian Monte

Carlo updates

acceptance A vector of TRUE/FALSE values indicates whether each proposed value is ac-

cepted

trajectory A list with 2 elements trajectory.q and trajectory.p. These are lists of

matrices contraining position and momentum values along trajectory in each

Hamiltonian Monte Carlo update.

## References

Chaudhuri, S., Mondal, D. and Yin, T. (2017) Hamiltonian Monte Carlo sampling in Bayesian empirical likelihood computation. *Journal of the Royal Statistical Society: Series B*.

4 ELHMC

Neal, R. (2011) MCMC for using Hamiltonian dynamics. *Handbook of Markov Chain Monte Carlo* (eds S. Brooks, A.Gelman, G. L.Jones and X.-L. Meng), pp. 113-162. New York: Taylor and Francis.

### **Examples**

```
## Not run:
## Suppose there are four data points (1, 1), (1, -1), (-1, -1), (-1, 1)
x = rbind(c(1, 1), c(1, -1), c(-1, -1), c(-1, 1))
\ensuremath{\mbox{\#\mbox{\#}}} If the parameter of interest is the mean, the smoothing function and
## its gradient would be
f <- function(params, x) {</pre>
x - params
df <- function(params, x) {</pre>
rbind(c(-1, 0), c(0, -1))
## Draw 50 samples from the Empirical Likelihood Bayesian posterior distribution
## of the mean, using initial values (0.96, 0.97) and standard normal distributions
## as priors:
normal_prior <- function(x) {</pre>
   exp(-0.5 * x[1] ^ 2) / sqrt(2 * pi) * exp(-0.5 * x[2] ^ 2) / sqrt(2 * pi)
}
normal_prior_log_gradient <- function(x) {</pre>
}
set.seed(1234)
mean.samples <- ELHMC(initial = c(0.96, 0.97), data = x, fun = f, dfun = df,
                      n.samples = 50, prior = normal_prior,
                      dprior = normal_prior_log_gradient)
plot(mean.samples$samples, type = "1", xlab = "", ylab = "")
## End(Not run)
```

# **Index**

ELHMC, 1